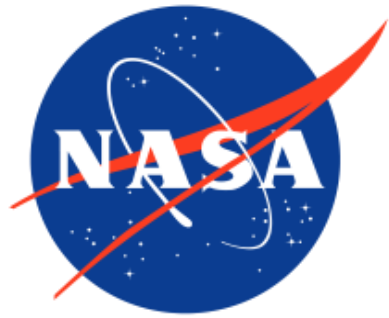


Functional ecology in the SBG Era: An assessment of the state of plant trait retrieval from imaging spectroscopy



Alexey N. Shiklomanov¹, Yoseline Angel^{1,2},
Dhruva Kathuria^{1,3}, Evan Lang^{1,4}

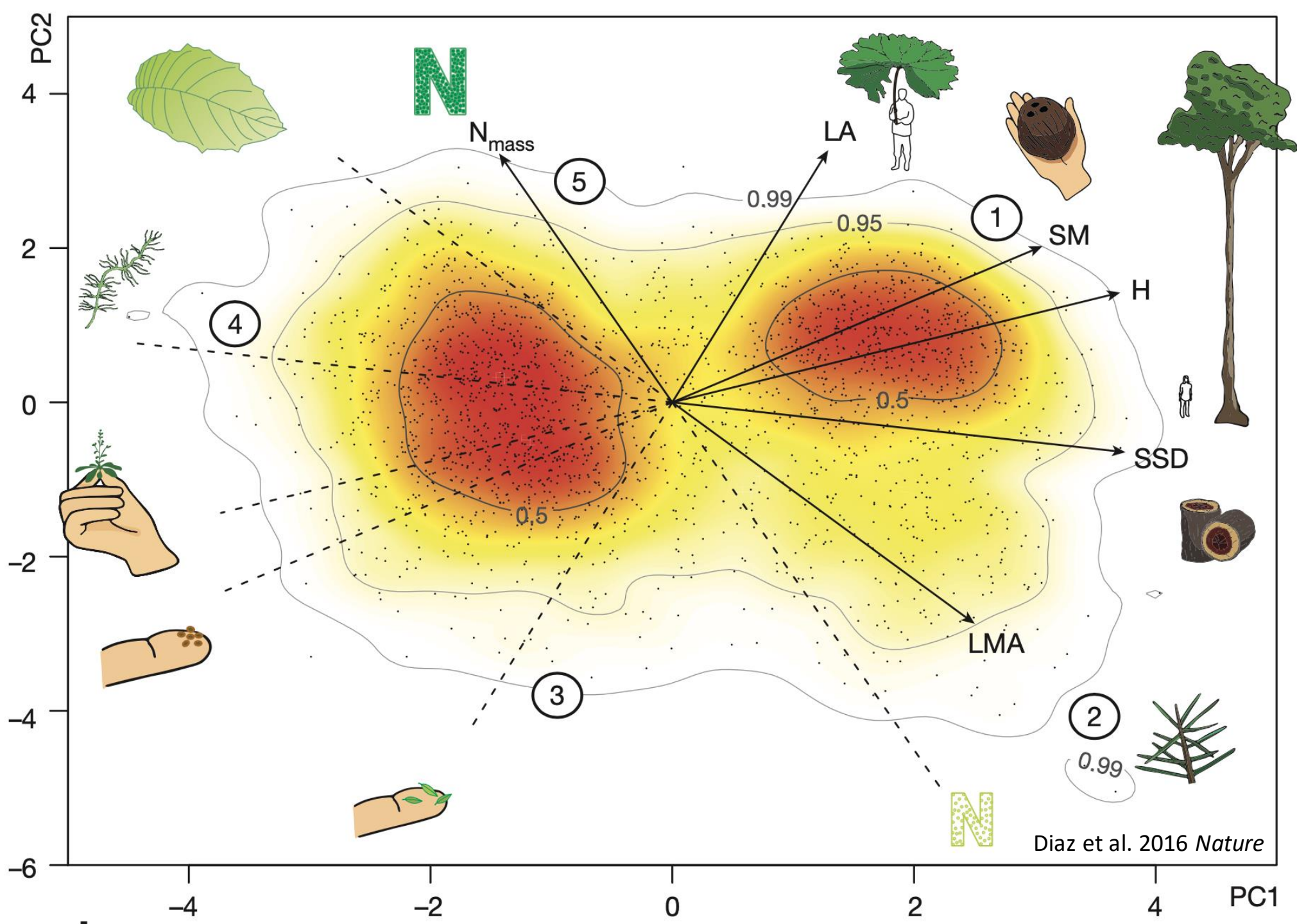
¹ NASA Goddard Space Flight Center; ² University of Maryland — ESSIC; ³ Morgan State University — GESTAR II; ⁴ Science Systems and Applications, Inc. (SSAI)



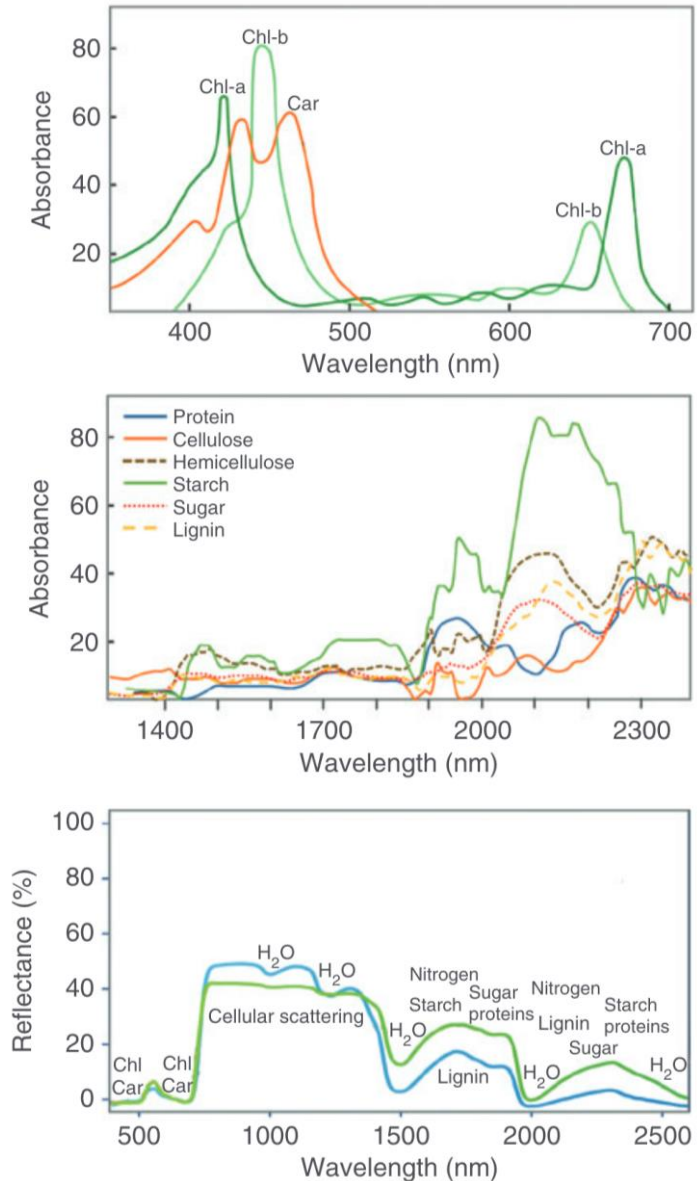
Cojo bay, CA
AVIRIS-NG (05/11/22)
RGB (2000-552-432nm)

Plant functional traits

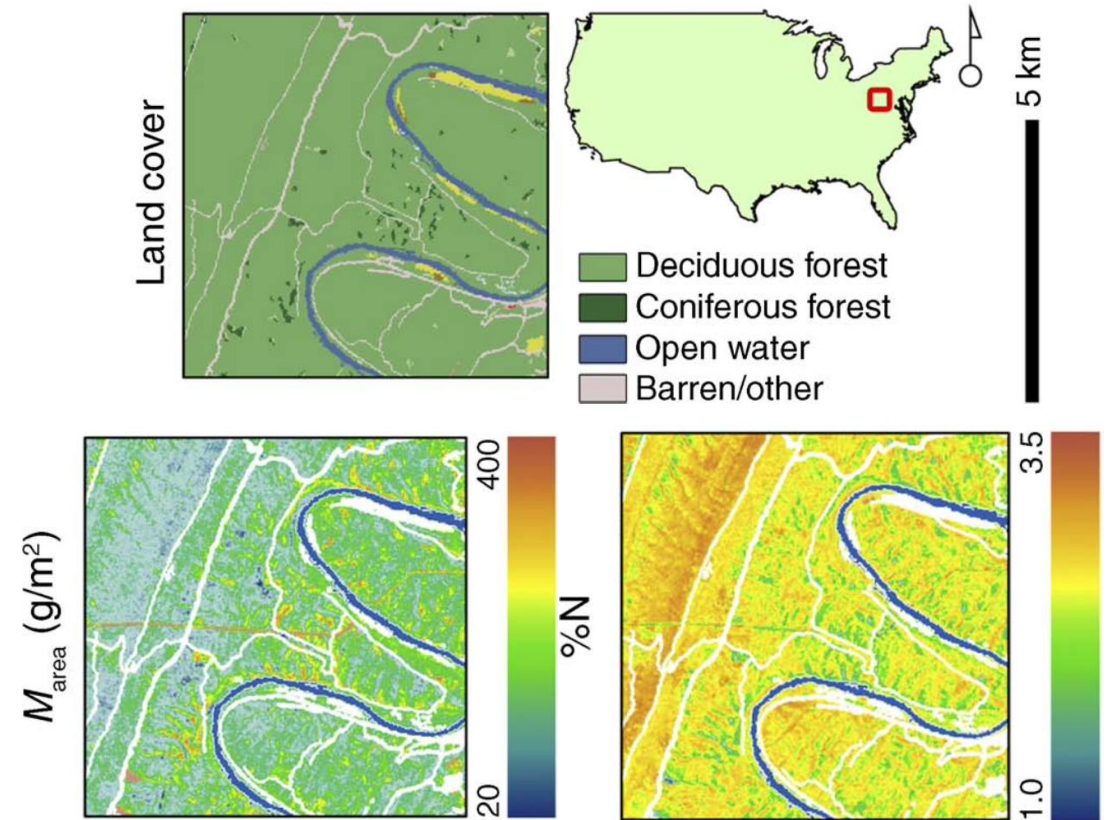
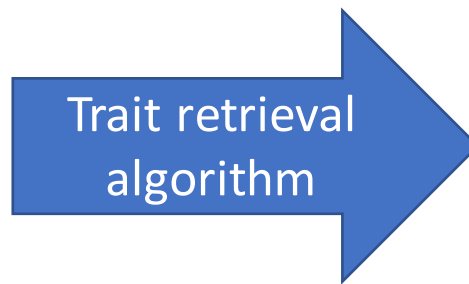
Measurable characteristics of plants that are closely related to function and fitness.



Leaf traits affect leaf reflectance...



...allowing us to estimate leaf traits from remote reflectance measurements

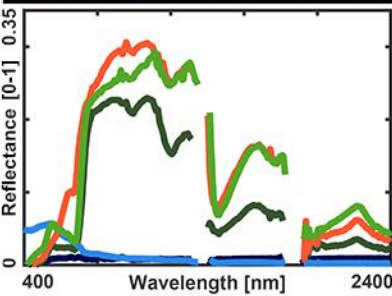
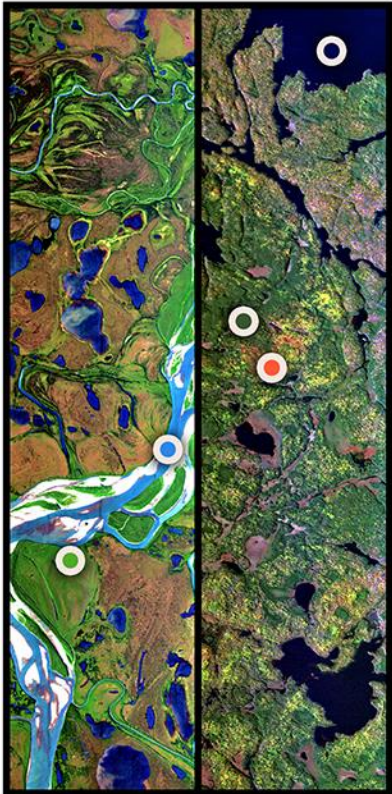


Singh et al. 2015 *Ecological Applications*

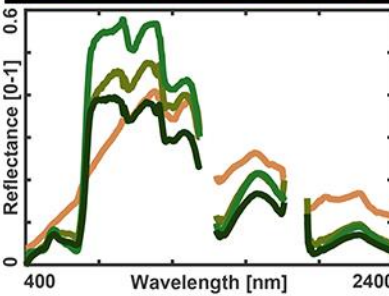
SBG provides data for many focus areas ...

... and will see the world in two critical spectral regions

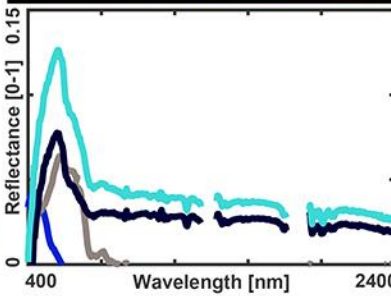
Ecosystems



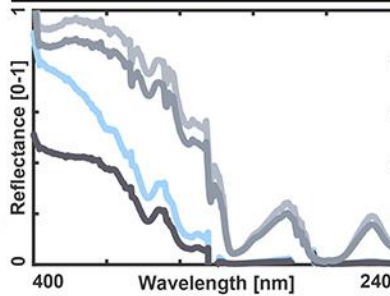
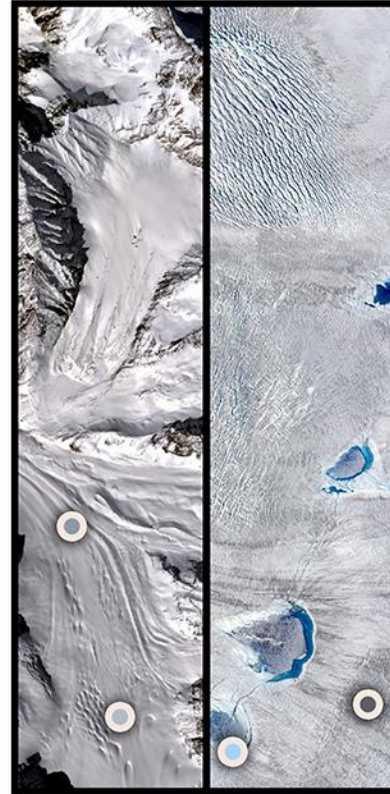
Agriculture



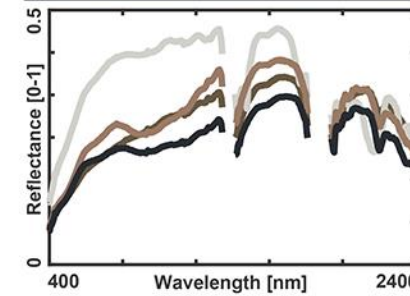
Coastal Zones



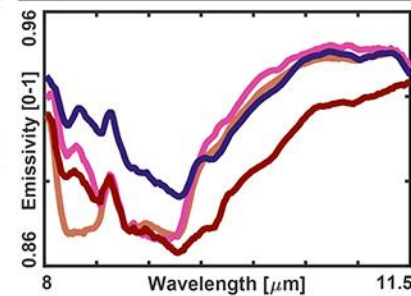
Snow and Ice



VSWIR



Minerals



TIR

Schneider et al. 2019 *Eos*

SBG will be one of the first satellites to acquire regular, global imaging spectroscopy data

~~(1) What are the "best" algorithms, at both leaf and canopy scales?~~

"Boring! Make new algorithms!"

OK.

- NASA review panel

- Shiklomanov et al.

(2) Why do these algorithms succeed (or fail), and under what conditions?

~~(3) How should we measure spectra to get the best trait estimates?~~

"Too late -- nobody cares!"
- NASA review panel

Fine, we'll look at flowers instead!
- Shiklomanov et al.

(2) Why do these algorithms succeed (or fail), and under what conditions?



“Visible”

“Invisible”

Clear physical basis

No direct physical basis



Water

Chlorophyll

LMA

Cellulose

Protein

Starch

Phenols

%N

%C

Mg

Ca

P

K

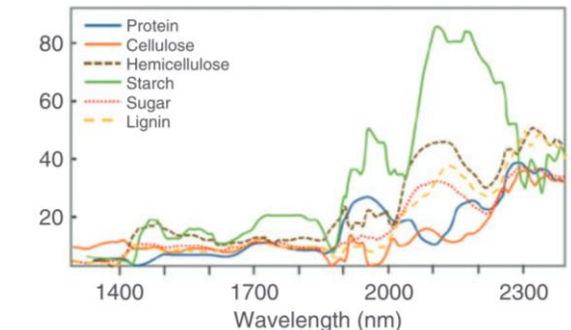
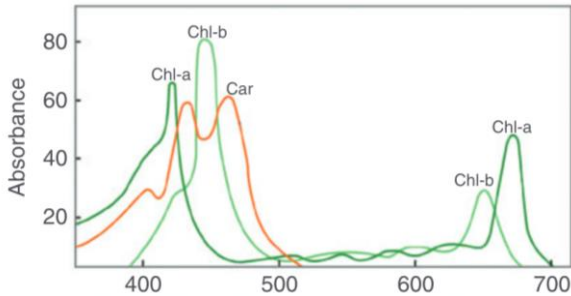
B

Fe

$\delta^{13}\text{C}$

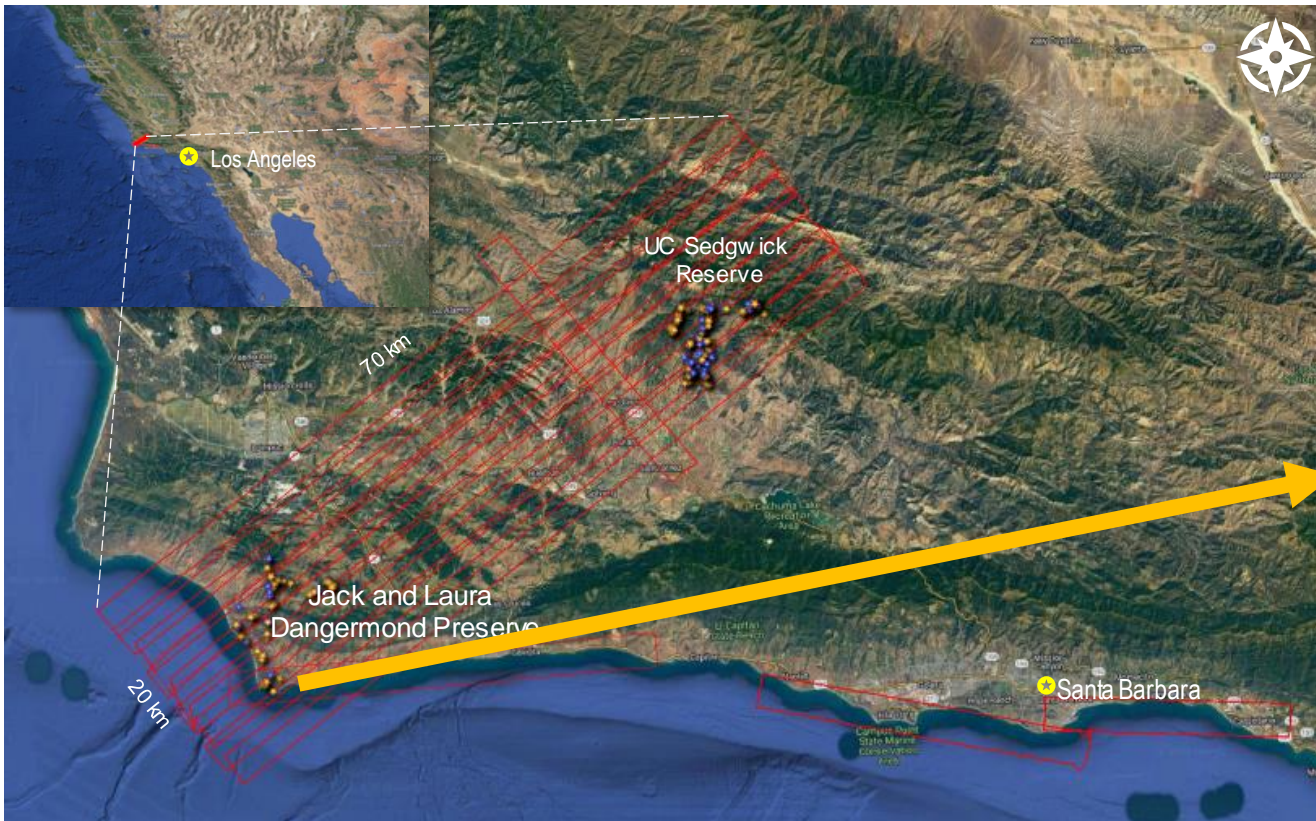
Vcmax

Jmax



Why is it possible to map “invisible” traits? What are we *really* seeing when we see “invisible” traits, in terms of correlations with other traits, structure, etc.? Can we leverage these correlations to make better algorithms?

(3) Flowers!

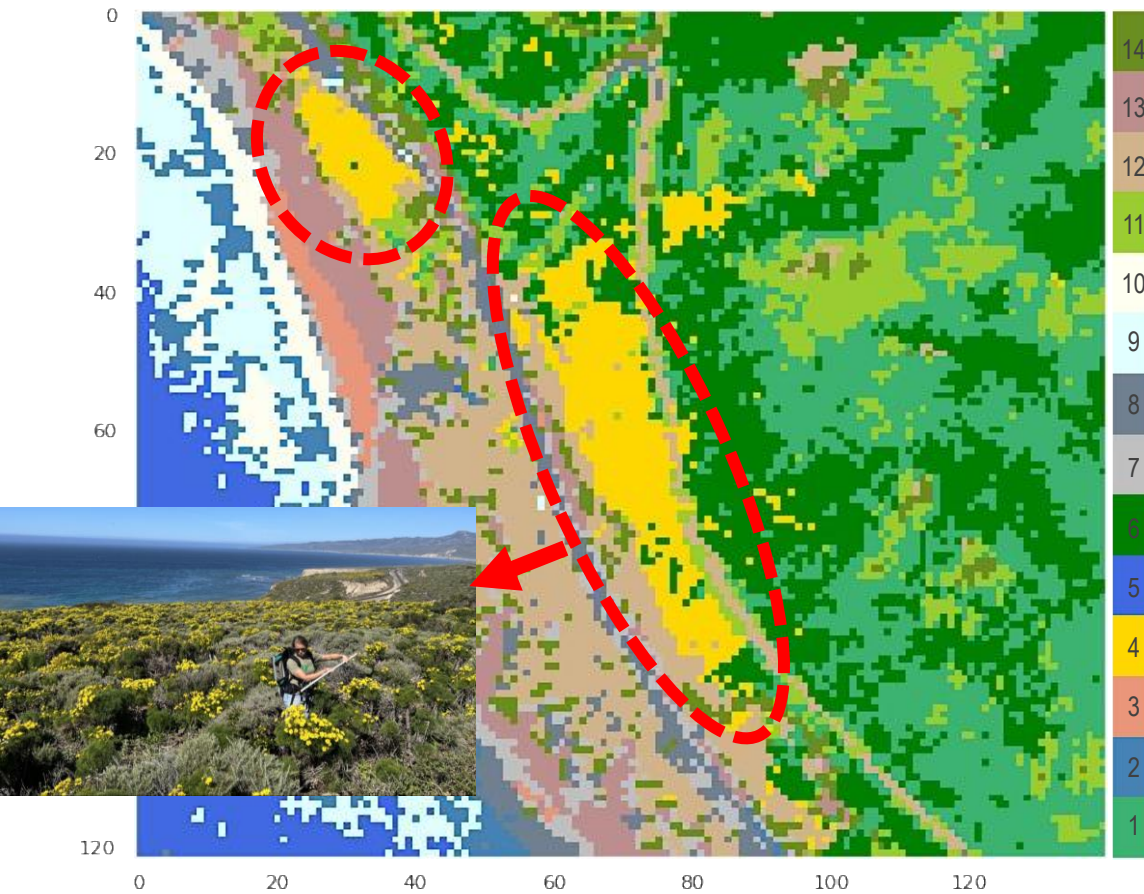


SBG High-Frequency Time series (SHIFT) — Weekly AVIRIS-NG flights during spring/summer 2021, with coordinated field sampling.

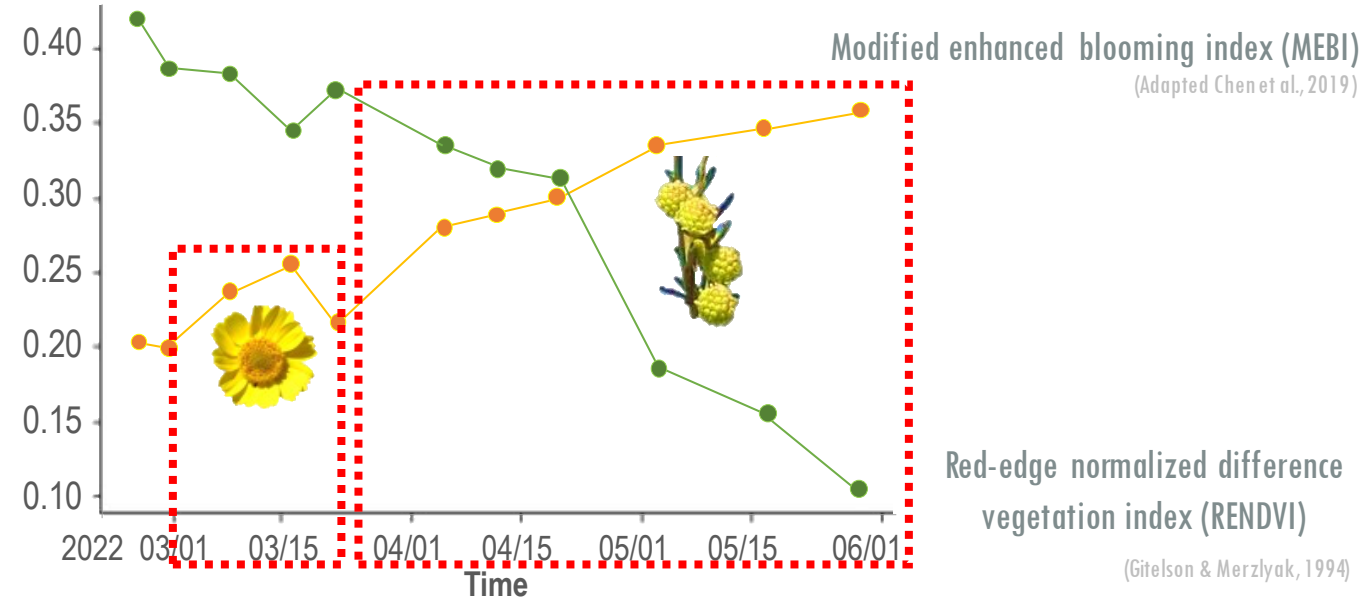


Dr. Yoseline Angel

Mapping flowering areas and studying flower phenology



Pixels classified as flowers are yellow. Other classes include ocean/dark (blue, white), soil (earth tones), and vegetation (greens).



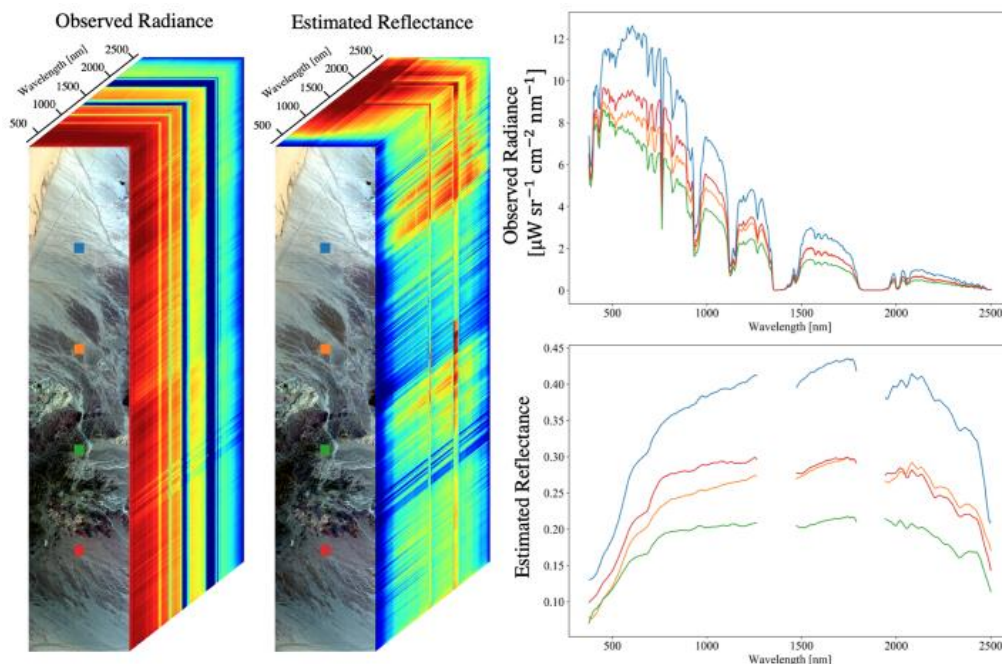
New vegetation index for yellow flowers shows **different temporal pattern than green vegetation index**, and highlights two distinct flowering cycles corresponding to two different species.



Dr. Yoseline Angel

Facilitating imaging spectroscopy data analysis with cloud computing

SHIFT airborne data are **huge** (300 GB per flight line; 5.4 TB total) and **complex** (high-dimensional, multi-file formats, multiple processing levels)



<https://shift-smce-user-guide.readthedocs.io>



Evan Lang

SHIFT project on NASA Science Managed Cloud Environment (SMCE) provides cloud-based interactive analysis capabilities (JupyterLab), scalable compute (SLURM) next to the SHIFT airborne data, and tools and documentation to make all of this easier!

Spectra Selection

```
# Create the RGB image plot
rgb_image = ds_rgb.hvplot.rgb(
    x='x', y='y', bands='wavelength', aspect = 'equal', frame_width=400).opts(
    tools=['hover', 'lasso_select'])

# Create streams
posxy = hv.streams.PointerXY(source=rgb_image, x=730302.5, y=-3819657.5)
sel = hv.streams.Lasso(source=rgb_image, geometry=np.array([[730302.5, 3819657.5]]))

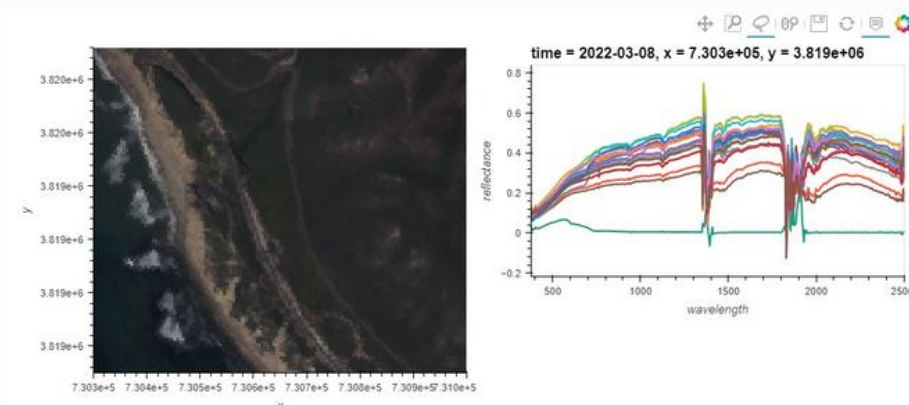
# Function to build a new spectral plot based on mouse hover positional
# Information retrieved from the RGB image using our full reflectance dataset
def point_spectra(x,y):
    return aoi.sel(x=x,y=y,method='nearest').hvplot.line(
        y='reflectance',x='wavelength', color='#1b9e77', frame_width=400)

def selected_info(geometry):
    x = find_nearest(aoi.x, geometry[:, 0])
    y = find_nearest(aoi.y, geometry[:, 1])
    points = set(list(zip(x, y)))

    list_of_lines = [aoi.sel(x=x, y=y, method='nearest').hvplot.line(
        y='reflectance',x='wavelength', frame_width=400) for x, y in points]
    return hv.Overlay(list_of_lines)

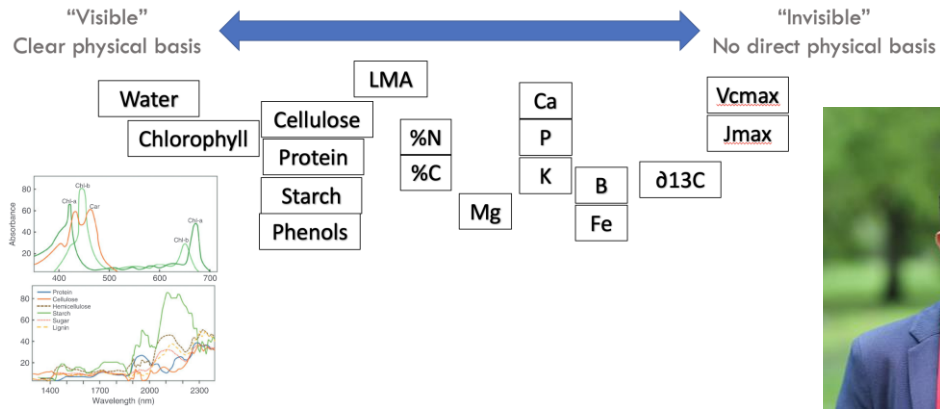
# Define the Dynamic Maps
point_dmap = hv.DynamicMap(point_spectra, streams=[posxy])
lasso_dmap = hv.DynamicMap(selected_info, streams=[sel])

# Plot the RGB image and Dynamic Maps side by side
(rgb_image + point_dmap*lasso_dmap)
```



Tell me more!

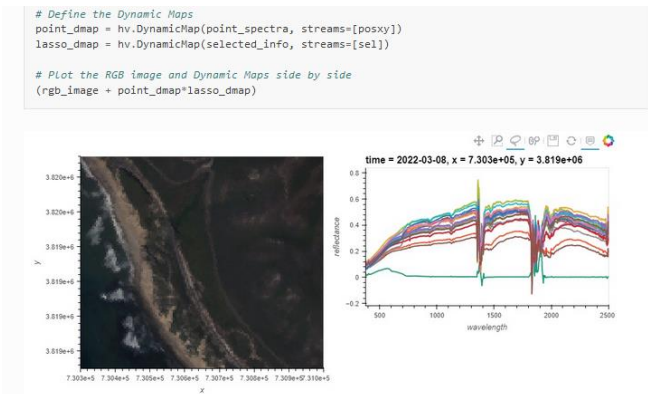
New retrieval algorithms: Dhruva's poster



Dr. Dhruva Kathuria

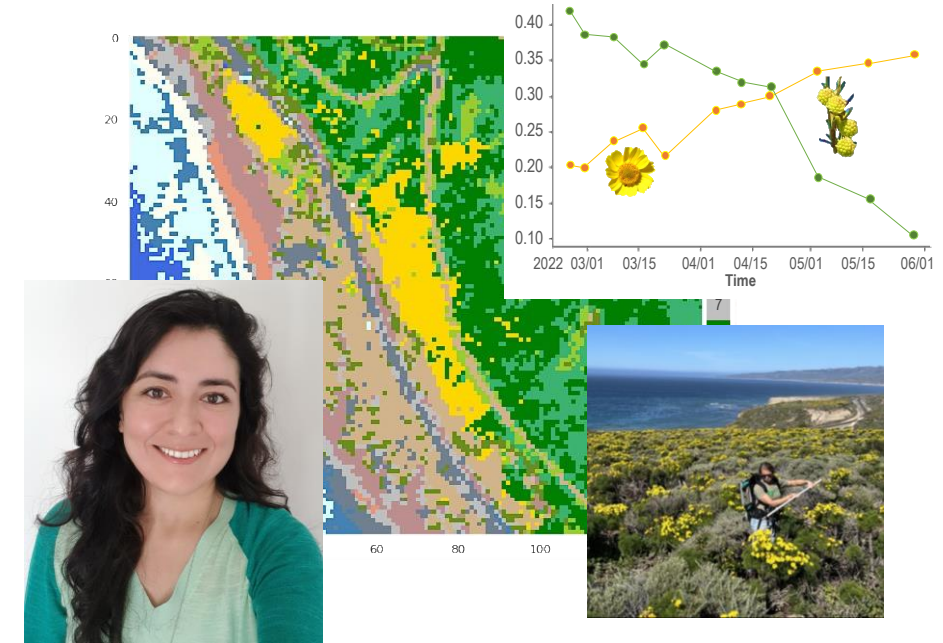
Cloud computing tools:

<https://shift-smce-user-guide.readthedocs.io>



Evan Lang

Flowers: Yoseline's poster



Dr. Yoseline Angel

...and see the 15-minute version of this talk at the
Terrestrial Ecology meeting, Tuesday, 9:55am,
Terrapin Ballroom